

Convex Optimization

(EE227A: UC Berkeley)

Lecture 16
(Proximal methods)

14 March, 2013



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Organizational

- ♠ HW3 will be released later today on bSpace
- ♠ Midterm to be out sometime on 18th
- ♠ HW2 solutions to be out before midterm released
- ♠ 19th March — review session to recap important material
- ♠ **21st March, 2013** — midterm due **beginning** of class.

Revisiting Gradient Projection

$$\min_{x \in \mathcal{X}} f(x)$$

Gradient projection

$$x^{k+1} = P(x^k - \alpha_k \nabla f(x^k))$$

where P denotes orthogonal projection onto \mathcal{X} .

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- ▶ Mimic unconstrained case proof
- ▶ Hinges on firm nonexpansivity of P
- ▶ Also key: stationarity property $x^* = P(x^* - \alpha \nabla f(x^*))$

Gradient projection – convergence

Lemma If x^* is optimal for problem, then $x^* = P(x^* - \alpha \nabla f(x^*))$

- ▶ Denote $g^* \equiv \nabla f(x^*)$ as before.
- ▶ **Optimality condition:** $\langle g^*, x - x^* \rangle \geq 0$ for all $x \in \mathcal{X}$.
- ▶ **Optimality for proj:** $z = Py \implies \langle z - y, x - z \rangle \geq 0 \forall x \in \mathcal{X}$.
- ▶ Plug $z \leftarrow x^*$, and $y \leftarrow x^* - \alpha g^*$,
 - $\langle x^* - y, x - x^* \rangle \geq 0 \implies \langle x^* - x^* + \alpha g^*, x - x^* \rangle \geq 0$
 - $\implies \langle \alpha g^*, x - x^* \rangle \geq 0$
 - $\implies \langle g^*, x - x^* \rangle \geq 0$
 - $\implies x^*$ is optimal.

Gradient projection – convergence

Now we show that $\|x^{k+1} - x^*\|_2 \leq \|x^k - x^*\|_2$

Shorthand: $u \equiv x^{k+1}$, $x \equiv x^k$, $g \equiv \nabla f(x^k)$

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Shorthand: $u \equiv x^{k+1}$, $x \equiv x^k$, $g \equiv \nabla f(x^k)$

$$\begin{aligned}\|u - x^*\|_2^2 &= \|P(x - \alpha g) - P(x^* - \alpha g^*)\|_2^2 \\ &\leq \|x - x^* - \alpha(g - g^*)\|_2^2 \\ &\leq \|x - x^*\|_2^2 + \alpha^2 \|g - g^*\|_2^2 - 2\alpha \langle g - g^*, x - x^* \rangle \\ &\leq \|x - x^*\|_2^2 + \alpha^2 \|g - g^*\|_2^2 - \frac{2\alpha}{L} \|g - g^*\|_2^2 \\ &= \|x - x^*\|_2^2 + \alpha \left(\alpha - \frac{2}{L}\right) \|g - g^*\|_2^2 \\ &= r_k^2 - \frac{1}{L} \|g - g^*\|_2^2 \quad (\text{if } \alpha = 1/L).\end{aligned}$$

Thus, we have in particular, $r_{k+1} \leq r_k \leq r_0$

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$$\begin{aligned} f(u) &\leq f(x) + \langle g, u - x \rangle + \frac{L}{2} \|u - x\|_2^2 \\ &= f(x) + \langle g, P(x - \alpha g) - Px \rangle + \frac{L}{2} \|u - x\|_2^2 \end{aligned}$$

Recall that $\|Pa - Pb\|_2^2 \leq \langle Pa - Pb, a - b \rangle$. Thus,

$$\begin{aligned} &\|P(x - \alpha g) - Px\|_2^2 \leq \langle P(x - \alpha g) - Px, x - \alpha g - x \rangle \\ &= -\alpha \langle g, P(x - \alpha g) - Px \rangle \\ \implies &-\alpha^{-1} \|u - x\|_2^2 \leq \langle g, P(x - \alpha g) - Px \rangle \end{aligned}$$

Which implies that

$$\begin{aligned} f(u) &\leq f(x) + \left(\frac{L}{2} - \frac{1}{\alpha}\right) \|u - x\|_2^2 \\ &= f(x) - \frac{L}{2} \|P(x - \alpha g) - x\|_2^2. \end{aligned}$$

Gradient projection – convergence

$$\begin{aligned} f^k &\geq f^{k+1} + \frac{L}{2} \|P(x^k - \alpha g^k) - x^k\|_2^2 \\ \implies f^0 - f^* &\geq f^{k+1} - f^* + \frac{L}{2} \sum_{i=0}^k \|P(x^i - \alpha g^i) - x^i\|_2^2. \end{aligned}$$

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- So far, we did not use convexity!
- **Rate of convergence** $O(1/k)$ using convexity (some more ideas needed though; see notes)

Proximal gradients – convergence

Proximal residual

$$\lim_{k \rightarrow \infty} \|\text{prox}_{\alpha r}(x^k - \alpha g^k) - x^k\|_2 = 0.$$

Proof: Essentially mimics gradient projection case (care needed).

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- ▶ Rate of convergence using convexity
- ▶ Analysis slightly more complicated (see notes)

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- ▶ Proximal-gradients: converges as $O(1/k)$ for C_L^1 cvx
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Can we obtain **optimal proximal-gradient** method?

Optimal Prox-grad – FISTA

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- $x^{k+1} = \text{prox}_{\alpha_k r}(y^k - \alpha_k \nabla \ell(y^k))$
- $t_{k+1} = (1 + \sqrt{4t_k^2 + 1})/2$
- $\lambda_k = (t_{k+1} + t_k - 1)/t_{k+1}$
- $y^{k+1} = x^k + \lambda_k(x^{k+1} - x^k)$

Remark: Achieves $O(1/k^2)$ optimal rate (assuming Lipschitzness).

Observe: Compare with optimal gradient method (very similar)

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More details in notes

Monotone operators

Set-valued mappings

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- ▶ **Empty relation:** \emptyset
- ▶ **Identity:** $I := \{(x, x) \mid x \in \mathbb{R}^n\}$
- ▶ **Zero:** $0 := \{(x, 0) \mid x \in \mathbb{R}^n\}$
- ▶ **Subdifferential:** $\partial f := \{(x, g) \mid x \in \mathbb{R}^n, g \in \partial f(x)\}$

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- ▶ **Subdifferential:** $\partial f := \{(x, g) \mid x \in \mathbb{R}^n, g \in \partial f(x)\}$
- ▶ We write $R(x)$ to mean $\{y \mid (x, y) \in R\}$.
- ▶ Example: $\partial f(x) = \{g \mid (x, g) \in \partial f\}$

Generalized equations

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- ▶ **Example:** Say $R \equiv \partial f$, then goal

$$0 \in R(x) = \partial f(x),$$

means we want to find an x that minimizes f .

Operations with relations

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- ▶ $S = \{(x + \lambda y, x) \mid (x, y) \in R\}$
- ▶ If $\lambda \neq 0$, shorthand $(x \leftarrow v, y \leftarrow (u - v)/\lambda)$

$$S := \{(u, v) \mid (u - v)/\lambda \in R(v)\}$$

Monotone operators

Def. The set valued operator $R \subset \mathbb{R}^n \times \mathbb{R}^n$ is called **monotone** if

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- ▶ Projection and proximity operators (recall firm nonexpansivity)

Generalize notion of monotonicity to vector world

Monotone operators

Exercise: Prove αR monotone if R monotone and $\alpha \geq 0$

Exercise: Prove R^{-1} monotone, if R is monotone

Exercise: If R, S monotone, and $\alpha \geq 0$, then $R + \alpha S$ is monotone.

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Exercise: If R, S monotone, and $\alpha \geq 0$, then $R + \alpha S$ is monotone.

Corollary: Resolvent operator of monotone operator is monotone.

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- ▶ That is, $y \in x + \lambda\partial f(x)$
- ▶ Equivalently, $x - y + \lambda\partial f(x) \ni 0$
- ▶ Nothing other than optimality condition for prox-operator!

$$\text{prox}_{\lambda f}(y) \equiv y \mapsto \underset{x}{\operatorname{argmin}} \frac{1}{2}\|x - y\|_2^2 + \lambda f(x)$$

Deriving proximal-grad method

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$$x \in \nabla \ell(x) + (I + \lambda \partial r)(x)$$

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$$x = (I + \lambda \partial r)^{-1}(x - \nabla \ell(x))$$

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$$x = \text{prox}_{\lambda r}(x - \nabla \ell(x))$$

Douglas-Rachford

$$f(x) + g(x)$$

If both f, g **nonsmooth**, ordinary splitting does not work!

How to solve it?

References

- ♠ S. Boyd. EE364B Lecture slides
- ♠ Yu. Nesterov. *Introductory Lectures on Convex Optimization*
- ♠ F. Dinuzzo. Lecture slides on large scale optimization