

Optimization for Machine Learning

Lecture 3: Basic problems, Duality

6.881: MIT

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Basic convex problems

Linear Programming

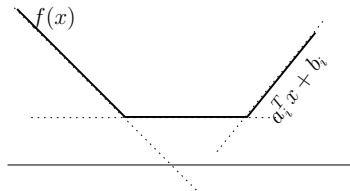
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Piecewise linear minimization is an LP

$$\min f(x) = \max_{1 \leq i \leq m} (a_i^T x + b_i)$$

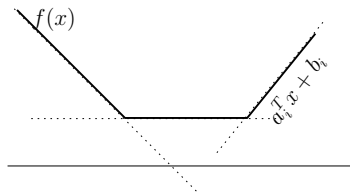


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$$\min_{x,t} \quad t \quad \text{s.t.} \quad a_i^T x + b_i \leq t, \quad i = 1, \dots, m.$$

Exercises



Formulate $\min_x \|Ax - b\|_1$ as an LP ($\|x\|_1 = \sum_i |x_i|$)



Formulate $\min_x \|Ax - b\|_\infty$ as an LP
($\|x\|_\infty = \max_{1 \leq i \leq n} |x_i|$)

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Explore: LP formulations for Markov Decision Processes (MDPs). MDPs are frequently used models in Reinforcement Learning, and in some cases admit nice LP formulations.

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Open Problem. Can we solve the system of inequalities $Ax \leq b$ in strongly polynomial time in the dimensions of the system, independent of the magnitudes of the coefficients? Best known result (Tardos, 1984) depends on coefficients of A but permits independence on magnitudes of b and the cost vector c .

N. Meggido, *On the complexity of linear programming*: [Click here!](#)

Quadratic Programming

$$\min \quad \frac{1}{2}x^T Ax + b^T x + c \quad \text{s.t. } Gx \leq h.$$

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Nonnegative least squares (NNLS)

$$\min \quad \frac{1}{2}\|Ax - b\|^2 \quad \text{s.t. } x \geq 0.$$

Exercise: Prove that NNLS always has a solution.

Regularized least-squares

Lasso

$$\min \quad \frac{1}{2} \|Ax - b\|_2^2 + \lambda \|x\|_1.$$

Exercise: How large must $\lambda > 0$ so that $x = 0$ is the optimum?

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Total-variation denoising

$$\min \quad \frac{1}{2} \|Ax - b\|_2^2 + \lambda \sum_{i=1}^{n-1} |x_{i+1} - x_i|.$$

Exercise: Is the total-variation term a norm? Prove or disprove.

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Group Lasso

$$\min_{x_1, \dots, x_T} \frac{1}{2} \left\| b - \sum_{j=1}^T A_j x_j \right\|_2^2 + \lambda \sum_{j=1}^T \|x_j\|_2.$$

Exercise: What is the dual norm of the regularizer above?

Robust LP as an SOCP

$$\begin{aligned} \min \quad & c^T x, \quad \text{s.t. } a_i^T x \leq b_i \quad \forall a_i \in \mathcal{E}_i \\ & \mathcal{E}_i := \{\bar{a}_i + P_i u \mid \|u\|_2 \leq 1\} \end{aligned}$$

Constraints are **uncertain** but with bounded uncertainty.

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(Adversarially) Robust LP formulation

$$\min_x \max_{\|u\|_2 \leq 1} \left\{ c^T x \mid a_i^T x \leq b_i, \quad a_i \in \mathcal{E}_i \right\}$$

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Second Order Cone Program

$$\min \quad c^T x, \quad \text{s.t. } \|P_i^T x\|_2 \leq -\bar{a}_i^T x + b_i, \quad i = 1, \dots, m.$$

SOCP constraint comes from:

$$\max_{\|u\|_2 \leq 1} (\bar{a}_i + P_i u)^T x = \bar{a}_i^T x + \|P_i^T x\|_2$$

Exercise: Give a quick argument for above equality.

Semidefinite Program (SDP)

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & c^T x \\ \text{s.t.} \quad & A(x) := A_0 + x_1 A_1 + x_2 A_2 + \dots + x_n A_n \succeq 0. \end{aligned}$$

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- ▶ Inequality $A \preceq B$ means $B - A$ is *semidefinite*
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- ▶ **Exercise:** Write LPs, QPs, and SOCPs as SDPs
- ▶ Feasible set of SDP is {semidefinite cone \cap hyperplanes}

Explore: Which convex problems **representable** as SDPs?
(This is an important topic in optimization theory).

Examples

♠ **Eigenvalue optimization:** $\min_x \lambda_{\max}(A(x))$

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♠ More examples – see CVX documentation and BV book

Explore: SDP relaxations of nonconvex probs: important technique, starting with MAXCUT SDP (Goemans-Williamson).

Explore: Sum-of-squares (SOS) optimization, Lasserre hierarchy of relaxations; see also: <https://www.sumofsquares.org>

Duality

(Weak duality, strong duality)

Primal problem

Let $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$ ($1 \leq i \leq m$). Generic *nonlinear program*

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & f_i(x) \leq 0, \quad 1 \leq i \leq m, \\ & x \in \{\text{dom } f \cap \text{dom } f_1 \cdots \cap \text{dom } f_m\}. \end{aligned} \tag{P}$$

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Domain: The set $\mathcal{X} := \{\text{dom } f \cap \text{dom } f_1 \cdots \cap \text{dom } f_m\}$

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- ▶ The variable x is the *primal variable*

Primal problem

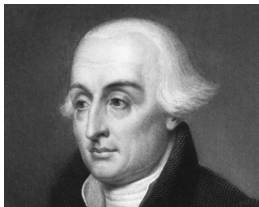
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Lagrangians and Duality



The reader will find no figures in this work. The methods which I set forth do not require either constructions or geometrical or mechanical reasonings: but only algebraic operations, subject to a regular and uniform rule of procedure.

—Joseph-Louis Lagrange
Preface to *Mécanique Analytique*

Lagrangian

To primal, associate *Lagrangian* $\mathcal{L} : \mathbb{R}^n \times \mathbb{R}_+^m \rightarrow (-\infty, \infty]$,

$$\mathcal{L}(x, \lambda) := f(x) + \sum_{i=1}^m \lambda_i f_i(x).$$

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♠ In other words,

$$\sup_{\lambda \in \mathbb{R}_+^m} \mathcal{L}(x, \lambda) = \begin{cases} f(x), & \text{if } x \text{ feasible,} \\ +\infty & \text{otherwise.} \end{cases}$$

Proof on next slide

Lagrangian – proof

$$\mathcal{L}(x, \lambda) := f(x) + \sum_{i=1}^m \lambda_i f_i(x).$$

► $f(x) \geq \mathcal{L}(x, \lambda), \forall x \in \mathcal{X}, \lambda \in \mathbb{R}_+^m$; so *primal optimal* (value)

$$p^* = \inf_{x \in \mathcal{X}} \sup_{\lambda \geq 0} \mathcal{L}(x, \lambda).$$

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- ▶ If x is feasible, each $f_i(x) \leq 0$, so $\sup_{\lambda} \sum_i \lambda_i f_i(x) = 0$

Dual value

$$\mathcal{L}(x, \lambda) := f(x) + \sum_{i=1}^m \lambda_i f_i(x).$$

Primal value $\in [-\infty, +\infty]$

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Dual value $\in [-\infty, +\infty]$

$$d^* = \sup_{\lambda \geq 0} \inf_{x \in \mathcal{X}} \mathcal{L}(x, \lambda).$$

Dual function

$$g(\lambda) := \inf_{x \in \mathcal{X}} \mathcal{L}(x, \lambda).$$

Observe that $g(\lambda)$ is **always** concave!

Weak duality theorem

Theorem. (Weak duality). $p^* \geq d^*$. (i.e., WD always holds)

Proof:

1. $f(x') \geq \mathcal{L}(x', \lambda) \quad \forall x' \in \mathcal{X}$
2. Thus, for any $x \in \mathcal{X}$, we have $f(x) \geq \inf_{x'} \mathcal{L}(x', \lambda) = g(\lambda)$
3. Now minimize over x on lhs to obtain

$$\forall \lambda \in \mathbb{R}_+^m \quad p^* \geq g(\lambda).$$

4. Thus, taking sup over $\lambda \in \mathbb{R}_+^m$ we obtain $p^* \geq d^*$.

Lagrangians - Exercise

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & f_i(x) \leq 0, \quad i = 1, \dots, m, \\ & h_i(x) = 0, \quad i = 1, \dots, p. \end{aligned}$$

Exercise: Show that we get the Lagrangian dual

$$g : \mathbb{R}_+^m \times \mathbb{R}^p : (\lambda, \nu) \mapsto \inf_x \mathcal{L}(x, \lambda, \nu),$$

Lagrange variable ν corresponds to the equality constraints.

Exercise: Prove that $p^* \geq \sup_{\lambda \geq 0, \nu \in \mathbb{R}^p} g(\lambda, \nu) = d^*$.

Exercises: Some duals

Derive Lagrangian duals for the following problems

- ▶ Least-norm solution of linear equations: $\min x^T x$ s.t. $Ax = b$
- ▶ Dual of an LP
- ▶ Dual of an SOCP
- ▶ Dual of an SDP
- ▶ Study example (5.7) in BV (binary QP)

Strong duality

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“Easy” necessary and sufficient conditions: **unknown**

Abstract duality gap theorem*

Theorem. Let $v : \mathbb{R}^m \rightarrow \mathbb{R}$ be the *primal value function*

$$v(u) := \inf \{f(x) \mid f_i(x) \leq u_i, 1 \leq i \leq m\}.$$

The following relations hold:

- 1 $p^* = v(0)$
- 2 $v^*(-\lambda) = \begin{cases} -g(\lambda) & \lambda \geq 0 \\ +\infty & \text{otherwise.} \end{cases}$
- 3 $d^* = v^{**}(0)$

So if $v(0) = v^{}(0)$ we have strong duality**

Remark: Conditions such as Slater's ensure $\partial v(0) \neq \emptyset$, which ensures v is finite and lsc at 0, whereby $v(0) = v^{**}(0)$ holds.

Slater's sufficient conditions

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & f_i(x) \leq 0, \quad 1 \leq i \leq m, \\ & Ax = b. \end{aligned}$$

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Constraint qualification: There exists $x \in \text{ri } \mathcal{X}$ s.t.

$$f_i(x) < 0, \quad Ax = b.$$

In words: there is a **strictly feasible** point.

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Theorem. Let the primal problem be convex. If there is a point that is *strictly feasible* for the non-affine constraints (merely feasible for affine), then strong duality holds. Moreover, in this case, the dual optimal is attained (i.e., $\partial v(0) \neq \emptyset$).

See BV §5.3.2 for a proof; (above, v is the primal value function)

Example with positive duality-gap

$$\min_{x,y} e^{-x} \quad x^2/y \leq 0,$$

over the domain $\mathcal{X} = \{(x, y) \mid y > 0\}$.

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$$\mathcal{L}(x, y, \lambda) = e^{-x} + \lambda x^2/y,$$

so dual function is

$$g(\lambda) = \inf_{x,y>0} e^{-x} + \lambda x^2/y = \begin{cases} 0 & \lambda \geq 0 \\ -\infty & \lambda < 0. \end{cases}$$

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Thus, $d^* = 0$, and gap is $p^* - d^* = 1$.

Here, we had **no strictly feasible** solution.

Example: Support Vector Machine (SVM)

$$\begin{aligned} \min_{x, \xi} \quad & \frac{1}{2} \|x\|_2^2 + C \sum_i \xi_i \\ \text{s.t.} \quad & Ax \geq 1 - \xi, \quad \xi \geq 0. \end{aligned}$$

Example: Support Vector Machine (SVM)

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$$\begin{aligned} g(\lambda, \nu) &:= \inf L(x, \xi, \lambda, \nu) \\ &= \begin{cases} \lambda^T \mathbf{1} - \frac{1}{2} \|A^T \lambda\|_2^2 & \lambda + \nu = C \mathbf{1} \\ +\infty & \text{otherwise} \end{cases} \\ d^* &= \max_{\lambda \geq 0, \nu \geq 0} g(\lambda, \nu) \end{aligned}$$

Exercise: Using $\nu \geq 0$, eliminate ν from above dual and obtain the canonical *dual SVM* formulation.

Example: norm regularized problems

$$\min_x f(x) + \|Ax\|$$

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Dual problem

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Say $\|\bar{y}\|_* < 1$, such that $A^T \bar{y} \in \text{ri}(\text{dom } f^*)$, then we have strong duality—for instance if $0 \in \text{ri}(\text{dom } f^*)$

Exercise. Write the constrained form of *group-lasso*:

$$\min_{x_1, \dots, x_T} \frac{1}{2} \left\| b - \sum_{j=1}^T A_j x_j \right\|_2^2 + \lambda \sum_{j=1}^T \|x_j\|_2.$$

Example: Dual via Fenchel conjugates

$$\min_x f_0(x) \quad \text{s.t.} \quad f_i(x) \leq 0 \quad (1 \leq i \leq m), \quad Ax = b.$$

Introduce ν and λ as dual variables; consider Lagrangian

$$\mathcal{L}(x, \lambda, \nu) := f_0(x) + \sum_i \lambda_i f_i(x) + \nu^T (Ax - b)$$

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$$\begin{aligned} \mathcal{L}(x, \lambda, \nu) &:= f_0(x) + \sum_i \lambda_i f_i(x) + \nu^T (Ax - b) \\ g(\lambda, \nu) &= \inf_x \mathcal{L}(x, \lambda, \nu) \end{aligned}$$

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$$g(\lambda, \nu) = -\nu^T b - F^*(-A^T \nu).$$

F^* seems rather opaque...

Example: Dual via Fenchel conjugates

Important trick: “variable splitting”

$$\min_x f_0(x) \quad \text{s.t.} \quad f_i(x_i) \leq 0, Ax = b$$

$x = x_i, i = 1, \dots, m.$

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$$x = x_i, i = 1, \dots, m.$$

$$\mathcal{L}(x, x_i, \lambda, \nu, \pi_i)$$
$$:= f_0(x) + \sum_i \lambda_i f_i(x_i) + \nu^T (Ax - b) + \sum_i \pi_i^T (x_i - x)$$

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$$= -\nu^T b + \inf_x \left(f_0(x) + \nu^T Ax - \sum_i \pi_i^T x \right) \\ + \sum_i \inf_{x_i} \left(\pi_i^T x_i + \lambda_i f_i(x_i) \right),$$

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$$\begin{aligned} \mathcal{L}(x, x_i, \lambda, \nu, \pi_i) &:= f_0(x) + \sum_i \lambda_i f_i(x_i) + \nu^T (Ax - b) + \sum_i \pi_i^T (x_i - x) \\ g(\lambda, \nu, \pi_i) &= \inf_{x, x_i} \mathcal{L}(x, x_i, \lambda, \nu, \pi_i) \\ &= -\nu^T b + \inf_x \left(f_0(x) + \nu^T Ax - \sum_i \pi_i^T x \right) \\ &\quad + \sum_i \inf_{x_i} \left(\pi_i^T x_i + \lambda_i f_i(x_i) \right), \\ &= -\nu^T b - f^* \left(-A^T \nu + \sum_i \pi_i \right) - \sum_i (\lambda_i f_i)^* (-\pi_i). \end{aligned}$$

(you may want to write $\sum_i \pi_i = s$)

Exercise: the variable splitting trick

$$\min_x f(x) + h(x).$$

Exercise: Fill in the details for the following steps

$$\min_{x,z} f(x) + h(z) \quad \text{s.t.} \quad x = z$$

$$L(x, z, \nu) = f(x) + h(z) + \nu^T(x - z)$$

$$g(\nu) = \inf_{x,z} L(x, z, \nu)$$

Strong duality: nonconvex example

Trust region subproblem (TRS)

$$\min \quad x^T A x + 2b^T x \quad x^T x \leq 1.$$

A is symmetric but not necessarily semidefinite!

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Theorem. TRS always has zero duality gap.

Proof: Read Section 5.2.4 of BV.

See the challenge problems on pg 18, Lect1

von Neumann minmax theorem*

(Simplified.) Let A be linear, C, D be compact convex sets.

$$\min_{x \in C} \max_{y \in D} \langle Ax, y \rangle = \max_{y \in D} \min_{x \in C} \langle Ax, y \rangle.$$

von Neumann minmax theorem*

(**Simplified.**) Let A be linear, C, D be compact convex sets.

$$\min_{x \in C} \max_{y \in D} \langle Ax, y \rangle = \max_{y \in D} \min_{x \in C} \langle Ax, y \rangle.$$

von Neumann proved this via fixed-point theory. By considering the Fenchel problem

$$\min_x \mathbb{1}_C(x) + \mathbb{1}_D^*(Ax),$$

we can conclude the theorem (some work required).