

Gradient Flow and Diffusion

Optimization for Machine Learning

Lecture 14

08 April, 2021

Background and Definitions

- Let \mathcal{P} denote the space of probability densities over \mathbb{R}^d
- We will briefly use the 2-Wasserstein distance, which is a metric over \mathcal{P} . It can be defined as

$$W_2(\mu_1, \mu_2) = \inf_{v \in \Gamma(\mu_1, \mu_2)} \sqrt{\mathbb{E}_{x \sim \mu_1} [\|v(x)\|_2^2]}$$

where $\Gamma(\mu_1, \mu_2)$ is a collection of maps from $\mathbb{R}^d \rightarrow \mathbb{R}^d$, defined as follows:

A map $v(x)$ belongs to $\Gamma(\mu_1, \mu_2)$ if and only if “ **μ_2 is the push-forward of μ under v** ”

In other words, “**if $x \sim \mu_1$, then $(x + v(x)) \sim \mu_2$** ”

Given any μ_1, μ_2 , let $V^{\mu_1 \rightarrow \mu_2} := \operatorname{argmin}_{v \in \Gamma(\mu_1, \mu_2)} \sqrt{\mathbb{E}_{x \sim \mu_1} [\|v(x)\|_2^2]}$ (always attained)

**note: the above definition of W_2 is equivalent to the standard definition only when μ_1, μ_2 are densities (i.e. no atoms)*

Background and Definitions

- Given some target density $\pi \in \mathbb{R}^d$, we define the Relative Entropy functional $\mathcal{H}_\pi: \mathcal{P} \rightarrow \mathbb{R}^+$ as

$$\mathcal{H}_\pi(\mu) := \int \mu(x) \log \left(\frac{\mu(x)}{\pi(x)} \right) dx$$

fact: $\mathcal{H}_\pi(\mu)$ is minimized at $\mu = \pi$, with $\mathcal{H}_\pi(\pi) = 0$.

Throughout this lecture, $\mathcal{H}_\pi(\cdot)$ plays the role of an “objective which we seek to minimize”

Motivating Problem

We would like to sample from the distribution $\pi^*(x) \propto \exp(-U(x))$, where $U(x)$ is **m -strongly convex** and has **L -Lipschitz gradients**.

A basic algorithm is the Langevin MCMC algorithm:

$$x_{k+1} = x_k - \eta \nabla U(x_k) + \sqrt{2\eta} \xi_k$$

where $\xi_k \sim \mathcal{N}(0, I)$ i.i.d

Let μ_k denote the distribution of x_k . Then

$$\mathcal{H}_{\pi^*}(\mu_{k+1}) \leq (1 - m\eta)\mathcal{H}_{\pi^*}(\mu_k) + \eta^2 dL^2$$

which implies

$$\mathcal{H}_{\pi^*}(\mu_k) \leq e^{-mk\eta} + \frac{\eta dL^2}{m}$$

Taking the continuous-time limit

The Langevin MCMC Algorithm:

$$\tilde{\mathbf{x}}_{(k+1)\eta} = \tilde{\mathbf{x}}_{k\eta} - \delta \nabla U(\tilde{\mathbf{x}}_{k\eta}) + \sqrt{2\delta} \xi_k$$

where $\xi_k \sim \mathcal{N}(0, I)$.

Guarantee:

$$\mathcal{H}_{\pi^*}(\tilde{\mu}_{(k+1)\eta}) \leq (1 - m\eta) \mathcal{H}_{\pi^*}(\tilde{\mu}_{k\eta}) + \eta^2 dL^2$$

By taking the limit of $\delta \rightarrow 0$, we obtain the Langevin Diffusion:

$$d\mathbf{x}_t = -\nabla U(\mathbf{x}_t) dt + \sqrt{2} dB_t$$

Guarantee:

$$\frac{d}{dt} \mathcal{H}_{\pi^*}(\mu_t) \leq -m \mathcal{H}_{\pi^*}(\mu_t)$$

A familiar algorithm : Gradient Descent in Euclidean Space

Objective: $\min_y f(y)$

If $f(y)$ is m -strongly convex, it satisfies, for all y_1, y_2

$$f(y_2) \geq f(y_1) + \langle \nabla f(y_1), y_2 - y_1 \rangle + \frac{m}{2} \|y_2 - y_1\|_2^2$$

the above implies “gradient domination”:

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

Gradient descent is given by

$$\tilde{y}^{k+1} = \tilde{y}^k - \eta \nabla f(\tilde{y}^k)$$

it satisfies (assuming L -Lipschitz gradients)

$$\begin{aligned} & f(\tilde{y}^{k+1}) - f(\tilde{y}^k) \\ & \leq -2m\eta (f(\tilde{y}^k) - f(y^*)) + \frac{\eta^2 L}{2} \|f(\tilde{y}^k) - f(y^*)\|_2^2 \end{aligned}$$

Continuous-time limit is gradient flow:

$$d y_t = -\nabla f(y_t) dt$$

it satisfies

$$\frac{d}{dt} f(y_t) - f(y^*) \leq -2m (f(y_t) - f(y^*))$$

Comparison of the two problems

Objective: $\min_{\mu \in \mathcal{P}} \mathcal{H}(\mu) := \min_{\mu \in \mathcal{P}} \int \mu(x) \log \left(\frac{\mu(x)}{\pi^*(x)} \right) dx$

If $U(x) = -\log \pi^*(x)$ is m -strongly convex, then

$\mathcal{H}(\mu)$ is m -geodesically-strongly convex (HWI Inequality)

$$\mathcal{H}(\mu_1) \geq \mathcal{H}(\mu_2) + \int \left\langle \nabla \log \frac{\mu_1(x)}{\pi^*(x)}, V^{1 \rightarrow 2}(x) \right\rangle \mu_1(x) dx + \frac{m}{2} \int \|V^{1 \rightarrow 2}(x)\|_2^2 \mu_1(x) dx$$

for all $\mu_1, \mu_2 \in \mathcal{P}$

$\mathcal{H}(\mu)$ is m -gradient dominant (Log-Sobolev Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu_1(x) dx$$

$\mathcal{H}(\mu)$ is lower bounded by W_2 distance (Talagrand Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \geq \frac{m}{2} W_2^2(\mu_1, \mu_2)$$

Objective: $\min_x f(x)$

$f(y)$ is m -strongly convex

$$f(y_2) \geq f(y_1) + \langle \nabla f(y_1), y_2 - y_1 \rangle + \frac{m}{2} \|y_2 - y_1\|_2^2$$

for all $y_1, y_2 \in \mathbb{R}^d$

$f(y)$ is m -gradient dominant

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

$f(y)$ is lower bounded by $\|y - y^*\|_2^2$

$$f(y) - f(y^*) \geq \frac{m}{2} \|y - y^*\|_2^2$$

Langevin Diffusion vs (Euclidean) Gradient Flow

$\mathcal{H}(\mu)$ is m -gradient dominant (Log-Sobolev Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx$$

$f(y)$ is m -gradient dominant

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

Gradient Flow wrt \mathcal{H}

$$\frac{\partial}{\partial t} \mu_t(x) = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$

Gradient Flow wrt f

$$d y_t = -\nabla f(y_t) dt$$

Sample Space Dynamics:

$$d x_t = -\nabla U(x_t) dt + \sqrt{2} dB_t$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} \mathcal{H}(\mu_t) - \mathcal{H}(\pi^*) &= - \int \left\| \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\|_2^2 \mu_t(x) dx \\ &\leq -2m(\mathcal{H}(\mu_t) - \mathcal{H}(\pi^*)) \end{aligned}$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} f(y_t) - f(y^*) &= -\|\nabla f(y_t)\|_2^2 \\ &\leq -2m(f(y_t) - f(y^*)) \end{aligned}$$

Part 1: Strong Convexity implies Gradient Dominance

$$\begin{aligned} \mathcal{H}(\mu_2) &\geq \mathcal{H}(\mu_1) + \int \left\langle \nabla \log \frac{\mu_1(x)}{\pi^*(x)}, V^{\mu_1 \rightarrow \mu_2}(x) \right\rangle \mu_1(x) dx + \frac{m}{2} \int \|V^{\mu_1 \rightarrow \mu_2}(x)\|_2^2 \mu_1(x) dx \\ \Rightarrow \mathcal{H}(\mu) - \mathcal{H}(\pi^*) &\leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx \end{aligned}$$

$$\begin{aligned} f(y_2) - f(y_1) &\geq \langle \nabla f(y_1), y_2 - y_1 \rangle + \frac{m}{2} \|y_2 - y_1\|_2^2 \\ \Rightarrow f(y) - f(y^*) &\leq \frac{1}{2m} \|\nabla f(y)\|_2^2 \end{aligned}$$

Proof: let $\mu_1 = \mu$, $y_2 = \pi^*$, then


$$\begin{aligned} \mathcal{H}(\mu) - \mathcal{H}(\mu^*) &\leq - \int \left\langle \nabla \log \frac{\mu(x)}{\pi^*(x)}, V^{\mu \rightarrow \pi^*}(x) \right\rangle \mu(x) dx - \frac{m}{2} \int \|V^{\mu \rightarrow \pi^*}(x)\|_2^2 \mu(x) dx \\ &\leq \int \sup_v \left(\left\langle \nabla \log \frac{\mu(x)}{\pi^*(x)}, v \right\rangle - \frac{m}{2} \|v\|_2^2 \right) \mu(x) dx \\ &\leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx \end{aligned}$$

Proof: let $y_1 = y$, $y_2 = y^*$, then

$$\begin{aligned} f(y) - f(y^*) &\leq \langle \nabla f(y), y - y^* \rangle - \frac{m}{2} \|y - y^*\|_2^2 \\ &\leq \sup_v \langle \nabla f(y), v \rangle - \frac{m}{2} \|v\|_2^2 \\ &\leq \frac{1}{2m} \|\nabla f(y)\|_2^2 \end{aligned}$$

Langevin Diffusion vs (Euclidean) Gradient Flow

$\mathcal{H}(\mu)$ is m -gradient dominant (Log-Sobolev Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx$$


$f(y)$ is m -gradient dominant

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

Gradient Flow wrt \mathcal{H}

$$\frac{\partial}{\partial t} \mu_t(x) = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$

Sample Space Dynamics:

$$d x_t = -\nabla U(x_t) dt + \sqrt{2} dB_t$$

Gradient Flow wrt f

$$d y_t = -\nabla U(y_t) dt$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} \mathcal{H}(\mu_t) - \mathcal{H}(\pi^*) &= - \int \left\| \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx \\ &\leq -2m(\mathcal{H}(\mu_t) - \mathcal{H}(\pi^*)) \end{aligned}$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} f(y_t) - f(y^*) &= -\|\nabla f(y_t)\|_2^2 \\ &\leq -2m(f(y_t) - f(y^*)) \end{aligned}$$

Part 2: The Dynamics in Probability Space

Sample-space Dynamics

$$d x_t = -\nabla U(x_t)dt + \sqrt{2}dB_t$$

Gradient Flow wrt f

$$d y_t = -\nabla U(y_t)dt$$

Fokker Planck Equation:


$$\begin{aligned} \frac{\partial}{\partial t} \mu_t(x) &= \operatorname{div}(\mu_t(x) \nabla U(x_t)) + \operatorname{Tr}(\nabla^2 \mu_t(x)) \\ &= -\operatorname{div}(\mu_t(x) \nabla \log \pi^*(x)) + \operatorname{div}(\mu_t(x) \nabla \log \mu_t(x)) \end{aligned}$$

Probability-space Dynamics

$$\frac{\partial}{\partial t} \mu_t(x) = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$

Langevin Diffusion vs (Euclidean) Gradient Flow

$\mathcal{H}(\mu)$ is m -gradient dominant (Log-Sobolev Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx$$



$f(y)$ is m -gradient dominant

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

Gradient Flow wrt \mathcal{H}

$$\frac{\partial}{\partial t} \mu_t(x) = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$

Sample Space Dynamics:

$$d x_t = -\nabla U(x_t) dt + \sqrt{2} dB_t$$


Gradient Flow wrt f

$$d y_t = -\nabla U(y_t) dt$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} \mathcal{H}(\mu_t) - \mathcal{H}(\pi^*) &= - \int \left\| \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\|_2^2 \mu_t(x) dx \\ &\leq -2m (\mathcal{H}(\mu_t) - \mathcal{H}(\pi^*)) \end{aligned}$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} f(y_t) - f(y^*) &= -\|\nabla f(y_t)\|_2^2 \\ &\leq -2m (f(y_t) - f(y^*)) \end{aligned}$$

Part 3: Evolution of the Objective

$$\begin{aligned}
 & \frac{\partial}{\partial t} \mathcal{H}(\mu_t) \\
 &= \frac{\partial}{\partial t} \int \mu_t(x) \log \frac{\mu_t(x)}{\pi^*(x)} dx \\
 &= \int \frac{\partial \mu_t(x)}{\partial t} \log \frac{\mu_t(x)}{\pi^*(x)} dx + \mu_t(x) \frac{\partial}{\partial t} \left(\log \frac{\mu_t(x)}{\pi^*(x)} \right) dx \\
 &= \int \frac{\partial \mu_t}{\partial t}(x) \log \frac{\mu_t(x)}{\pi^*(x)} dx + \int \frac{\partial \mu_t}{\partial t}(x) dx \\
 &= \int \frac{\partial \mu_t}{\partial t}(x) \log \frac{\mu_t(x)}{\pi^*(x)} dx \\
 &= \int \left(\operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right) \right) \cdot \log \frac{\mu_t(x)}{\pi^*(x)} dx \\
 &= - \int \left\langle \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right), \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\rangle dx \\
 &= - \int \left\| \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\|_2^2 \mu_t(x) dx \\
 &\leq -2m (\mathcal{H}(\mu_t) - \mathcal{H}(\pi^*))
 \end{aligned}$$

By Log-Sobolev Inequality

$$\begin{aligned}
 & \frac{d}{dt} f(y_t) - f(y^*) \\
 &= \left\langle \nabla f(y_t), \frac{dy_t}{dt} \right\rangle \\
 &= \langle \nabla f(y_t), -\nabla f(y_t) \rangle \\
 &= -\|\nabla f(y_t)\|_2^2 \\
 &\leq -2m (f(y_t) - f(y^*))
 \end{aligned}$$

From Part 2:


$$\frac{\partial \mu_t(x)}{\partial t} = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$

Integration by parts: for any $g: \mathbb{R}^d \rightarrow \mathbb{R}$ and $v: \mathbb{R}^d \rightarrow \mathbb{R}^d$ such that $\|v(x)\|_2$ decays sufficiently fast as $\|x\|_2 \rightarrow \infty$

$$\int g(x) \operatorname{div}(v(x)) dx = - \int \langle \nabla g(x), v(x) \rangle dx$$

Langevin Diffusion vs (Euclidean) Gradient Flow

$\mathcal{H}(\mu)$ is m -gradient dominant (Log-Sobolev Inequality)

$$\mathcal{H}(\mu) - \mathcal{H}(\pi^*) \leq \frac{1}{2m} \int \left\| \nabla \log \frac{\mu(x)}{\pi^*(x)} \right\|_2^2 \mu(x) dx$$



$f(y)$ is m -gradient dominant

$$f(y) - f(y^*) \leq \frac{1}{2m} \|\nabla f(y)\|_2^2$$

Gradient Flow wrt \mathcal{H}

$$\frac{\partial}{\partial t} \mu_t(x) = \operatorname{div} \left(\mu_t(x) \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right)$$


Sample Space Dynamics:

$$d x_t = -\nabla U(x_t) dt + \sqrt{2} dB_t$$


Gradient Flow wrt f

$$d y_t = -\nabla U(y_t) dt$$

Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} \mathcal{H}(\mu_t) - \mathcal{H}(\pi^*) &= - \int \left\| \nabla \log \frac{\mu_t(x)}{\pi^*(x)} \right\|_2^2 \mu_t(x) dx \\ &\leq -2m (\mathcal{H}(\mu_t) - \mathcal{H}(\pi^*)) \end{aligned}$$


Gradient Flow Convergence

$$\begin{aligned} \frac{d}{dt} f(y_t) - f(y^*) &= -\|\nabla f(y_t)\|_2^2 \\ &\leq -2m (f(y_t) - f(y^*)) \end{aligned}$$

Part 4: Discretization and Iteration Complexity

Langevin MCMC

$$\tilde{x}^{k+1} = \tilde{x}^k - \eta \nabla U(\tilde{x}^k) + \sqrt{2\delta\xi^k}$$

Can be re-written as a continuous-time stochastic process:

$$d\tilde{x}_t = -\nabla U(\tilde{x}_{k\eta})dt + \sqrt{2\delta}dB_t \quad \text{for } t \in [k\eta, (k+1)\eta)$$

Again by Fokker Planck, for $t \in [k\eta, (k+1)\eta)$:

$$\begin{aligned} \frac{\partial}{\partial t} \tilde{\mu}_t(x) &= \text{div} \left(\tilde{\mu}_t(x) \left(\nabla \log \tilde{\mu}_t(x) + \nabla U(x_{k\eta}) \right) \right) \\ &= \text{div} \left(\tilde{\mu}_t(x) \left(\nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right) \right) + \text{div} \left(\tilde{\mu}_t(x) \left(\nabla U(\tilde{x}_{k\eta}) - \nabla U(\tilde{x}) \right) \right) \end{aligned}$$

$$\begin{aligned} &\mathcal{H}(\tilde{\mu}_{(k+1)\eta}) - \mathcal{H}(\tilde{\mu}_{k\eta}) \\ &= \int_{k\eta}^{(k+1)\eta} \text{div} \left(\tilde{\mu}_t(x) \left(\nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right) \right) \cdot \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} dt \\ &\quad + \int_{k\eta}^{(k+1)\eta} \text{div} \left(\tilde{\mu}_t(x) \left(\nabla U(\tilde{x}_{k\eta}) - \nabla U(\tilde{x}) \right) \right) \cdot \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} dt \\ &\leq \int_{k\eta}^{(k+1)\eta} \left(\left\| \nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right\|_2^2 + L \left\| \nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right\|_2 \right) \|\tilde{x}_t - \tilde{x}_{k\eta}\|_2 dt \end{aligned}$$

Gradient Descent

$$\tilde{y}^{k+1} = \tilde{y}^k - \eta \nabla f(\tilde{y}^k)$$

Can be re-written as a continuous-time process:

$$\begin{aligned} d\tilde{y}_t &= -\nabla f(\tilde{y}_{k\eta})dt && \text{for } t \in [k\eta, (k+1)\eta) \\ &= -\nabla f(\tilde{y}_t) + \left(\nabla f(\tilde{y}_t) - \nabla f(\tilde{y}_{k\eta}) \right) \end{aligned}$$

Then

$$\begin{aligned} &f(\tilde{y}_{(k+1)\eta}) - f(\tilde{y}_{k\eta}) \\ &= \int_{k\eta}^{(k+1)\eta} \left\langle \nabla f(\tilde{y}_t), \frac{d}{dt} \tilde{y}_t \right\rangle dt \\ &= \int_{k\eta}^{(k+1)\eta} \langle \nabla f(\tilde{y}_t), -\nabla f(\tilde{y}_t) \rangle dt \\ &\quad + \int_{k\eta}^{(k+1)\eta} \langle \nabla f(\tilde{y}_t), \nabla f(\tilde{y}_t) - \nabla f(\tilde{y}_{k\eta}) \rangle dt \\ &\leq \int_{k\eta}^{(k+1)\eta} \left(-\|\nabla f(\tilde{y}_t)\|_2^2 + L \|\nabla f(\tilde{y}_t)\|_2 \|\tilde{y}_t - \tilde{y}_{k\eta}\|_2 \right) dt \\ &\leq -\eta \|\nabla f(\tilde{y})\|_2^2 + \frac{L\eta^2}{2} \|\nabla f(\tilde{y})\|_2^2 \end{aligned}$$

Part 4: Discretization and Iteration Complexity

$$\begin{aligned}
 & \mathcal{H}(\tilde{\mu}_{(k+1)\eta}) - \mathcal{H}(\tilde{\mu}_{k\eta}) \\
 &= \int_{k\eta}^{(k+1)\eta} \int \operatorname{div} \left(\tilde{\mu}_t(x) \left(\nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right) \right) \cdot \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} dx dt \\
 &\quad + \int_{k\eta}^{(k+1)\eta} \int \operatorname{div} \left(\tilde{\mu}_t(x) \left(\nabla U(\tilde{x}_{k\eta}) - \nabla U(\tilde{x}) \right) \right) \cdot \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} dx dt \\
 &\leq \int_{k\eta}^{(k+1)\eta} \int - \left\| \nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right\|_2^2 \tilde{\mu}_t(x) dx dt \\
 &\quad + L \int_{k\eta}^{(k+1)\eta} \int \left\| \nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right\|_2 \|x - \tilde{x}_{k\eta}\|_2 \tilde{\mu}_t(x) dx dt \\
 &\leq -\frac{1}{2} \int_{k\eta}^{(k+1)\eta} \int \left\| \nabla \log \frac{\tilde{\mu}_t(x)}{\pi^*(x)} \right\|_2^2 dx dt \\
 &\quad + \frac{L^2}{2} \int_{k\eta}^{(k+1)\eta} \int \|x - \tilde{x}_{k\eta}\|_2^2 \tilde{\mu}_t(x) dx dt
 \end{aligned}$$

$$\begin{aligned}
 \frac{L^2}{2} \int_{k\eta}^{(k+1)\eta} \int \|x - \tilde{x}_{k\eta}\|_2^2 \tilde{\mu}_t(x) dx dt &= \frac{L^2}{2} \int_{k\eta}^{(k+1)\eta} \mathbb{E} \left[\|\tilde{x}_t - \tilde{x}_{k\eta}\|_2^2 \right] dt \\
 &= o(L^2 \eta^2 d)
 \end{aligned}$$

Gradient Descent

$$\tilde{y}^{k+1} = \tilde{y}^k - \eta \nabla f(\tilde{y}^k)$$

Can be re-written as a continuous-time process:

$$\begin{aligned}
 d\tilde{y}_t &= -\nabla f(\tilde{y}_{k\eta}) dt && \text{for } t \in [k\eta, (k+1)\eta) \\
 &= -\nabla f(\tilde{y}_t) + \left(\nabla f(\tilde{y}_t) - \nabla f(\tilde{y}_{k\eta}) \right)
 \end{aligned}$$

Then

$$\begin{aligned}
 & f(\tilde{y}_{(k+1)\eta}) - f(\tilde{y}_{k\eta}) \\
 &= \int_{k\eta}^{(k+1)\eta} \left\langle \nabla f(\tilde{y}_t), \frac{d}{dt} \tilde{y}_t \right\rangle dt \\
 &= \int_{k\eta}^{(k+1)\eta} \langle \nabla f(\tilde{y}_t), -\nabla f(\tilde{y}_t) \rangle dt \\
 &\quad + \int_{k\eta}^{(k+1)\eta} \langle \nabla f(\tilde{y}_t), \nabla f(\tilde{y}_t) - \nabla f(\tilde{y}_{k\eta}) \rangle dt \\
 &\leq \int_{k\eta}^{(k+1)\eta} -\|\nabla f(\tilde{y}_t)\|_2^2 + L \|\nabla f(\tilde{y}_t)\|_2 \|\tilde{y}_t - \tilde{y}_{k\eta}\|_2 dt \\
 &\leq -\eta \|\nabla f(\tilde{y})\|_2^2 + \frac{L\eta^2}{2} \|\nabla f(\tilde{y})\|_2^2
 \end{aligned}$$

References

“Rapid convergence of the unadjusted langevin algorithm: Isoperimetry suffices” -SS Vempala, A Wibisono 2019

“Generalization of an inequality by Talagrand and links with the logarithmic Sobolev inequality” - F Otto, C Villani 2000